# KAPITEL 3 BERUHT AUF EINEM AUSZUG AUS DEM FOLGENDEN VORTRAG: 

A tutorial on Database Theory and a talk on database query answering under updates

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Humboldt-Universität zu Berlin

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## Example database and two queries

| Movie |  |
| :--- | :--- |
| Name | Actor |
| Alien | Sigourney Weaver |
| Blade Runner | Harrison Ford |
| Blade Runner | Sean Young |
| Brazil | Jonathan Pryce |
| Brazil | Kim Greist |
| Casablanca | Humphrey Bogart |
| Casablanca | Ingrid Bergmann |
| Gravity | Sandra Bullock |
| Gravity | George Clooney |
| Resident Evil | Milla Jovovich |
| Terminator | Arnold Schwarzenegger |
| Terminator | Linda Hamilton |
| Terminator | Michael Biehn |
| $\vdots$ | $\vdots$ |
|  |  |


| Programme |  |  |  | Movietitle | Time |
| :--- | :--- | :--- | :---: | :---: | :---: |
| Cinema | Casablanca | $17: 30$ |  |  |  |
| Babylon | Gravity | $20: 15$ |  |  |  |
| Babylon | Blade Runner | $15: 30$ |  |  |  |
| Casablanca | Alien | $18: 15$ |  |  |  |
| Casablanca | Blade Runner | $20: 30$ |  |  |  |
| Casablanca | Resident Evil | $20: 30$ |  |  |  |
| Casablanca | Kino International | Casablanca |  |  |  |
| Kino International | Brazil | $20: 00$ |  |  |  |
| Kino International | Brazil | $22: 00$ |  |  |  |
| Moviemento | Gravity | $17: 00$ |  |  |  |
| Moviemento | Gravity | $19: 30$ |  |  |  |
| Moviemento | Alien | $22: 00$ |  |  |  |
| Urania | Resident Evil | $20: 00$ |  |  |  |
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Return all titles of movies $y$ in which Sigourney Weaver stars:

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Return all tuples $(x, y)$ of cinemas $x$ and movie titles $y$ such that $x$ plays movie $y$ in which Sigourney Weaver stars:

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Conjunctive queries!

## Example database and two queries

A logician's point of view:

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\text { Programme } & : \text { a 3-ary relation symbol } P \\
\text { database schema } & : \text { relational signature } \sigma:=\{M, D\}
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| adb | $:$ | $D=\left(M^{D}, P^{D}\right)$, where |
| $M^{D}$ | $:$ | a finite subset of dom ${ }^{2}$ |
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| dom | $:$ a fixed, infinite domain of potential db entries |  |

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## Query evaluation

Consider a query language $L$ (e.g., SQL, conjunctive queries CQ, first-order logic FO).

Let $\varphi\left(x_{1}, \ldots, x_{k}\right)$ be a query of signature $\sigma$, formulated in $L$.
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$\varphi(D):=\llbracket \varphi\left(x_{1}, \ldots, x_{k}\right) \rrbracket(D):=$

$$
\left\{\left(a_{1}, \ldots, a_{k}\right) \in \operatorname{adom}(D)^{k}:(\operatorname{adom}(D), D) \models \varphi\left[\frac{a_{1} \cdots a_{k}}{x_{1} \cdots x_{k}}\right]\right\}
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Special case $k=0$ : Boolean queries:
Evaluate $\varphi()$ on $D \quad$ means $\quad$ Decide if $(\operatorname{adom}(D), D) \models \varphi$

## Complexity of query evaluation

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Typical results obtained in database theory:

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CAVEAT: These notions \& results cannot handle updates of the db !


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- Enumerate the tuples in $\varphi(D)$
- Dynamic setting:

Tuples may be inserted into or deleted from $D$

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First-Order Queries on Bounded Degree Databases

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For the static setting: tight characterisation of the tractable CQs:
Boolean: [Grohe, Schwentick, Segoufin 2001], [Grohe 2007], [Marx 2010], [Marx 2013]
counting: [Dalmau, Jonsson 2004], [Chen, Mengel 2015], [Greco, Scarcello 2015]
enumeration: [Bulatov et al. 2012], [Bagan, Durand, Grandjean 2007]
I.e.: Update time $n^{O(1)}$ is well-understood!

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For the static setting: tight characterisation of the tractable CQs:
Boolean: [Grohe, Schwentick, Segoufin 2001], [Grohe 2007], [Marx 2010], [Marx 2013]
counting: [Dalmau, Jonsson 2004], [Chen, Mengel 2015], [Greco, Scarcello 2015]
enumeration: [Bulatov et al. 2012], [Bagan, Durand, Grandjean 2007]
I.e.: Update time $n^{O(1)}$ is well-understood!

Interesting: Sub-linear update time

## Scenario

- Input:
[Berkholz, Keppeler, S., PODS'17]
- Database $D$ arbitrary
- query $\varphi\left(x_{1}, \ldots, x_{k}\right)$
- Preprocessing:

Build a suitable data structure that represents $D$ and $\varphi(D)$

- Output:

For Boolean queries:

- Decide if $D \models \varphi$

For $k$-ary queries:

- Compute the number of tuples in $\varphi(D)$
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## q-hierarchical CQs

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This solves OMv in total time $O\left(n^{3-\varepsilon}\right)$ \&

Intractability result for Boolean CQs that are not q-hierarchical
The OuMv-problem:
[Henzinger et al., STOC'15] Input: a Boolean $n \times n$-matrix $M$ and
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## Intractability result for counting CQs that are not q-hierarchical

The OV-problem:
[cf. R. Williams, 2005]
Input: two sets $U$ and $V$ of $n$ Boolean vectors of dimension $d:=\left\lceil\log ^{2} n\right\rceil$
Task: decide if there exist $u \in U$ and $v \in V$ with $u^{\top} v=0$
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## Efficient evaluation of a fragment of CQs

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Theorem (Upper bound):
For every CQ that is q-hierarchical, there is a dynamic data structure that has constant update time and allows to

- answer a Boolean CQ,
- count the number of result tuples,
- enumerate the result relation with constant delay.


## q-hierarchical queries

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\varphi(x, y, z):=R(x) \wedge E(x, y) \wedge F(x, z)
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& |\varphi(D)|=\sum_{v \in R^{D}}\left|N_{E}^{+}(v)\right| \cdot\left|N_{F}^{+}(v)\right|
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- COUNT: store $\left|N_{E}^{+}(v)\right|,\left|N_{F}^{+}(v)\right|, \sum_{v \in R^{0}}\left|N_{E}^{+}(v)\right| \cdot\left|N_{F}^{+}(v)\right|$


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Lemma: A CQ $\varphi(\bar{x})$ is q-hierarchical $\Longleftrightarrow$ every connected component of $\varphi(\bar{x})$ has a q-tree.

## Data structure for q-hierarchical queries

$\varphi\left(x, y, z, y^{\prime}, z^{\prime}\right)=\left(R x y z \wedge R x y z^{\prime} \wedge E x y \wedge E x y^{\prime} \wedge S x y z\right)$


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Related work: [Idris, Ugarte, Vansummeren, SIGMOD'17]: q-hierarchical queries are also efficient in practice!

## Overview

## Introduction

## Conjunctive Queries on Arbitrary Databases

First-Order Queries on Bounded Degree Databases

## FO+MOD queries and $\mathrm{FOC}(\mathbb{P})$ queries

| Movie |  |
| :--- | :--- |
| Name | Actor |
| Alien | Sigourney Weaver |
| Blade Runner | Harrison Ford |
| Blade Runner | Sean Young |
| Brazil | Jonathan Pryce |
| Brazil | Kim Greist |
| Casablanca | Humphrey Bogart |
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| Gravity | Sandra Bullock |
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| Resident Evil | Milla Jovovich |
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## Is the number of movies with Sigourney Weaver even? <br> In FO+MOD: <br> $\exists^{0 \bmod 2} y \operatorname{Movie}(y$, "Sigourney Weaver")

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FO+MOD $=$ extension of first-order logic with modulo-counting quantifiers $\exists^{i \bmod m}$ y $\psi(y, \bar{z})$

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| Resident Evil | Milla Jovovich |
| Terminator | Arnold Schwarzenegger |
| Terminator | Linda Hamilton |
| Terminator | Michael Biehn |
| $\vdots$ | $\vdots$ |

Is the number of movies with

## Sigourney Weaver even?

In FO+MOD:
$\exists^{0 \bmod 2} y \operatorname{Movie}(y$, "Sigourney Weaver")
In $\operatorname{FOC}(\mathbb{P})$ :
$P_{\text {even }}(\#(y) . M o v i e(y$, "Sigourney Weaver") )

FO+MOD $=$ extension of first-order logic with modulo-counting quantifiers $\exists^{i \bmod m}$ y $\psi(y, \bar{z})$

Let $\mathbb{P}$ be a collection of numerical predicates. E.g., $\mathbb{P}$ may contain the predicates $\llbracket P_{\text {even }} \rrbracket=\{i \in \mathbb{Z}: i$ is even $\}$ and $\llbracket P_{\leqslant \rrbracket} \rrbracket=\left\{(i, j) \in \mathbb{Z}^{2}: i \leqslant j\right\}$.

## $\mathrm{FO}+\mathrm{MOD}$ queries and $\mathrm{FOC}(\mathbb{P})$ queries

| Movie |  |
| :--- | :--- |
| Name | Actor |
| Alien | Sigourney Weaver |
| Blade Runner | Harrison Ford |
| Blade Runner | Sean Young |
| Brazil | Jonathan Pryce |
| Brazil | Kim Greist |
| Casablanca | Humphrey Bogart |
| Casablanca | Ingrid Bergmann |
| Gravity | Sandra Bullock |
| Gravity | George Clooney |
| Resident Evil | Milla Jovovich |
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FOC $(\mathbb{P})=$ extension of first-order logic with formulas of the form
$P\left(t_{1}, \ldots, t_{r}\right)$ for $P \in \mathbb{P}$ of arity $r$, and where each $t_{i}$ is a counting term built using integers,,$+ \cdot$, and basic counting terms $t(\bar{x})$ of the form $\# \bar{y} \cdot \psi(\bar{x}, \bar{y})$

## Bounded degree databases

Graph $G=(V, E)$ :
degree of a node $v$ : the number of neighbours of $v$ in $G$ degree of $G: \max \{\operatorname{degree}(v): v \in V\}$

Database $D$ : degree of $D$ : degree of the Gaifman graph of $D$

Gaifman graph of $D$ :
the graph $G=(V, E)$ with $V=\operatorname{adom}(D)$ and an edge between two distinct nodes $a, b \in V$ iff some tuple in some relation of $D$ contains $a$ and $b$

## Known results for the static setting (i.e., without updates)

FO query evaluation on dbs of degree $\leqslant d$ Boolean queries:

- evaluation in linear time

Known results for the static setting (i.e., without updates) FO query evaluation on $d b s$ of degree $\leqslant d$

## Boolean queries:

- evaluation in linear time
- evaluation in time $f(\varphi, d)\|D\|$, for

$$
f(\varphi, d)=2^{d^{2 O(\|\varphi\|)}}=3-\exp (\|\varphi\|+\lg \lg d)
$$

and the 3-fold exponential blow-up is unavoidable assuming FPT $\neq \mathrm{AW}[*]$.

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- enumeration with constant delay and linear-time preprocessing (Durand, Grandjean 2007)

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Similar results for other classes of databases

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New: Generalisation to the dynamic setting and FO+MOD [Berkholz, Keppeler, S., ICDT'17] and FOC(P) [Kuske, S., LICS'17]

## Scenario

- Input:
- Database D
of degree $\leqslant d$
- query $\varphi\left(x_{1}, \ldots, x_{k}\right)$ in $\operatorname{FOC}(\mathbb{P})[\sigma]$
- Preprocessing:

Build a suitable data structure that represents $D$ and $\varphi(D)$

- Output:

For Boolean queries:

- Decide if $D \models \varphi$

For $k$-ary queries:

- Compute the number of tuples in $\varphi(D)$
- Test for a given tuple $\bar{a}$ whether $\bar{a} \in \varphi(D)$
- Enumerate the tuples in $\varphi(D)$
- Dynamic setting:

Tuples may be inserted into or deleted from $D$

## Scenario

- Input:
- Database D
of degree $\leqslant d$
- query $\varphi\left(x_{1}, \ldots, x_{k}\right)$
in $\operatorname{FOC}(\mathbb{P})[\sigma]$
data complexity
in time $O(\|D\|)$
- Preprocessing:

Build a suitable data structure that represents $D$ and $\varphi(D)$

- Output:

For Boolean queries:

- Decide if $D \models \varphi$

For $k$-ary queries:

- Compute the number of tuples in $\varphi(D)$
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## Scenario

- Input:
- Database $D$
of degree $\leqslant d$
- query $\varphi\left(x_{1}, \ldots, x_{k}\right)$
in $\operatorname{FOC}(\mathbb{P})[\sigma]$
- Preprocessing:
$D$ and $\varphi(D)$
- Output:

For Boolean queries:

- Decide if $D \models \varphi$
in constant time
For $k$-ary queries:
- Compute the number of tuples in $\varphi(D)$
- Test for a given tuple $\bar{a}$ whether $\bar{a} \in \varphi(D)$
- Enumerate the tuples in $\varphi(D)$
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- Database D
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- Preprocessing:
$D$ and $\varphi(D)$
- Output:

For Boolean queries:

- Decide if $D \models \varphi$
in constant time
For $k$-ary queries:
- Compute the number of tuples in $\varphi(D) \quad$ in constant time
- Test for a given tuple $\bar{a}$ whether $\bar{a} \in \varphi(D)$
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- Enumerate the tuples in $\varphi(D)$ with constant delay
- Dynamic setting: update data structure in constant time Tuples may be inserted into or deleted from $D$


## Scenario

 [Berkholz, Keppeler, S., ICDT'17]- Input:
- Database D
of degree $\leqslant d$
combined complexity
- query $\varphi\left(x_{1}, \ldots, x_{k}\right)$ in FO+MOD[ $\left.\sigma\right]$
- Preprocessing: $f(\varphi, d)=$ $3-\exp (\|\varphi\|+\lg \lg d)$

Build a suitable data structure that represents $D$ and $\varphi(D)$

- Output:

For Boolean queries:

- Decide if $D \models \varphi$
in constant time
For $k$-ary queries:
- Compute the number of tuples in $\varphi(D) \quad$ in constant time
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combined complexity $f(\varphi, d)=$ $3-\exp (\|\varphi\|+\lg \lg d)$ Build a suitable data structure that represents $D$ and $\varphi(D)$
- Output:

For Boolean queries:

- Decide if $D \models \varphi$

For $k$-ary queries:

- Compute the number of tuples in $\varphi(D)$
in time $O(1)$
- Test for a given tuple $\bar{a}$ whether $\bar{a} \in \varphi(D)$
- Enumerate the tuples in $\varphi(D)$
- Dynamic setting: update data structure in time $f(\varphi, d)$ Tuples may be inserted into or deleted from $D$


## Scenario

- Input:
- Database D
- query $\varphi\left(x_{1}, \ldots, x_{k}\right)$ in FO+MOD[ $\left.\sigma\right]$
- Preprocessing:
- Output:

For Boolean queries:

- Decide if $D \models \varphi$

For $k$-ary queries:

- Compute the number of tuples in $\varphi(D)$
in time $O(1)$
- Test for a given tuple $\bar{a}$ whether $\bar{a} \in \varphi(D)$
in time $O\left(k^{2}\right)$
- Enumerate the tuples in $\varphi(D)$
- Dynamic setting: update data structure in time $f(\varphi, d)$ Tuples may be inserted into or deleted from $D$


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- Database D
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Proof method: use Hanf normal form for FO+MOD


## Hanf normal form for FO+MOD

- A type $\tau$ with $k$ centres and radius $r$ :


Example type with $k=4$ centres and radius $r=1$

## Hanf normal form for FO+MOD

- A type $\tau$ with $k$ centres and radius $r$ :


Example type with $k=4$ centres and radius $r=1$

- $\mathcal{N}_{r}^{D}(\bar{b})$ is the induced substructure of $D$ on

$$
N_{r}^{D}(\bar{b})=N_{r}^{D}\left(b_{1}\right) \cup \cdots \cup N_{r}^{D}\left(b_{k}\right)
$$

where

$$
N_{r}^{D}\left(b_{i}\right)=\left\{a \in \operatorname{adom}(D): \operatorname{dist}^{D}\left(b_{i}, a\right) \leqslant r\right\}
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N_{r}^{D}\left(b_{i}\right)=\left\{a \in \operatorname{adom}(D): \operatorname{dist}^{D}\left(b_{i}, a\right) \leqslant r\right\}
$$

- Sphere-formula $\operatorname{sph}_{\tau}(\bar{x})$ :

$$
(D, \bar{a}) \models \operatorname{sph}_{\tau}(\bar{x}) \quad \Longleftrightarrow \quad\left(\mathcal{N}_{r}^{D}(\bar{a}), \bar{a}\right) \cong \tau
$$

## Hanf normal form for FO+MOD

A Hanf normal form $\psi(\bar{x})$ is a Boolean combination of

- sphere-formulas $\operatorname{sph}_{\rho}(\bar{x})$ and
- Hanf-sentences $\exists^{\geqslant m} y \operatorname{sph}_{\tau}(y)$ and $\exists^{i \bmod m} y \operatorname{sph}_{\tau}(y)$ where $\tau$ is a type with 1 centre and radius $r$.


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Two queries $\varphi(\bar{x})$ and $\psi(\bar{x})$ are $d$-equivalent iff

$$
(D, \bar{a}) \models \varphi \quad \Longleftrightarrow \quad(D, \bar{a}) \models \psi
$$

for all dbs $D$ of degree $\leqslant d$.

## Hanf normal form for $\mathrm{FO}+\mathrm{MOD}$

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(D, \bar{a}) \models \varphi \quad \Longleftrightarrow \quad(D, \bar{a}) \models \psi
$$

for all dbs $D$ of degree $\leqslant d$.

Theorem (Heimberg, Kuske, S., LICS'16)
There is an algorithm which receives as input a degree bound $d \geqslant 2$ and a $\mathrm{FO}+\mathrm{MOD}[\sigma]$-formula $\varphi(\bar{x})$, and constructs a d-equivalent formula $\psi(\bar{x})$ in Hanf normal form.
The algorithm's runtime is $f(\varphi, d)=3-\exp (\|\varphi\|+\lg \lg d)$.

## Main result for Boolean queries

Theorem
There is a dynamic algorithm that receives as input

- a degree bound $d \geqslant 2$,
- a Boolean FO+MOD[ $\sigma$ ]-query $\varphi$, and
- a db D of degree $\leqslant d$,
and computes
- within $f(\varphi, d)\|D\|$ preprocessing time a data structure
- that can be updated in time $f(\varphi, d)$ and allows to return the query result $\varphi(D)$ with answer time $O(1)$.

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f(\varphi, d)=3-\exp (\|\varphi\|+\lg \lg d)
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$$

Proof Idea: Step 1: Transform $\varphi$ into Hanf normal form $\psi$.

## Proof idea (by example)

$$
\psi=\exists^{0 \bmod 2} y \operatorname{sph}_{\tau}(y) \wedge \exists^{0 \bmod 2} y \operatorname{sph}_{\rho}(y)
$$

## Proof idea (by example)

$\psi=\exists^{0 \bmod 2} y \operatorname{sph}_{\tau}(y) \wedge \exists^{0 \bmod 2} y \operatorname{sph}_{\rho}(y)$
Let $\tau$ be the type with 1 center and radius 2 :


Let $\rho$ be the type with 1 center and radius 2 :


## Proof idea (by example)

$\psi=\exists^{0 \bmod 2} y \operatorname{sph}_{\tau}(y) \wedge \exists^{0 \bmod 2} y \operatorname{sph}_{\rho}(y)$
Let $\tau$ be the type with 1 center and radius 2 :


Let $\rho$ be the type with 1 center and radius 2 :


Data structure: $\quad \mathrm{A}[\tau]=0, \quad \mathrm{~A}[\rho]=0$

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Database:


## Proof idea (by example)

$\psi=\exists^{0 \bmod 2} y \operatorname{sph}_{\tau}(y) \wedge \exists^{0 \bmod 2} y \operatorname{sph}_{\rho}(y)$
Let $\tau$ be the type with 1 center and radius 2 :


Let $\rho$ be the type with 1 center and radius 2 :


Data structure: $\quad \mathrm{A}[\tau]=1 \quad, \mathrm{~A}[\rho]=0$
Database:


## Proof idea (by example)

$\psi=\exists^{0 \bmod 2} y \operatorname{sph}_{\tau}(y) \wedge \exists^{0 \bmod 2} y \operatorname{sph}_{\rho}(y)$
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Let $\tau$ be the type with 1 center and radius 2 :


Let $\rho$ be the type with 1 center and radius 2 :


Data structure: $\quad \mathrm{A}[\tau]=0 \quad, \quad \mathrm{~A}[\rho]=1$
Database:


## Proof idea (by example)

$\psi=\exists^{0 \bmod 2} y \operatorname{sph}_{\tau}(y) \wedge \exists^{0 \bmod 2} y \operatorname{sph}_{\rho}(y)$
Let $\tau$ be the type with 1 center and radius 2 :


Let $\rho$ be the type with 1 center and radius 2 :


Data structure: $\quad \mathrm{A}[\tau]=0, \quad \mathrm{~A}[\rho]=2$
Database:


## Main result for Boolean queries

Theorem
There is a dynamic algorithm that receives as input

- a degree bound $d \geqslant 2$,
- a Boolean FO+MOD[ $\sigma$ ]-query $\varphi$, and
- a db D of degree $\leqslant d$,
and computes
- within $f(\varphi, d)\|D\|$ preprocessing time a data structure
- that can be updated in time $f(\varphi, d)$ and allows to return the query result $\varphi(D)$ with answer time $O(1)$.

$$
f(\varphi, d)=3-\exp (\|\varphi\|+\lg \lg d)
$$

## Main result for enumeration

Theorem
There is a dynamic algorithm that receives as input

- a degree bound $d \geqslant 2$,
- a k-ary FO+MOD[ $\sigma$-query $\varphi(\bar{x})$, and
- a db D of degree $\leqslant d$,
and computes
- within $f(\varphi, d)\|D\|$ preprocessing time a data structure
- that can be updated in time $f(\varphi, d)$ and allows to enumerate $\varphi(D)$ with delay $O\left(k^{3}\right)$.

$$
f(\varphi, d)=3-\exp (\|\varphi\|+\lg \lg d)
$$

## Main result for enumeration

Theorem
There is a dynamic algorithm that receives as input

- a degree bound $d \geqslant 2$,
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Proof Idea:

## Proof idea: Reduction to coloured graphs

```
Input:
Database \(D\)
FO+MOD-query \(\varphi\left(x_{1}, \ldots, x_{k}\right)\)
```

Same approach as in [Durand, S., Segoufin, PODS'14], but now we have to take care of updates!

## Proof idea: Reduction to coloured graphs

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\text { Input: } \\
\text { Database } D \\
\text { FO }+ \text { MOD-query } \varphi\left(x_{1}, \ldots, x_{k}\right)
\end{gathered} \underbrace{\downarrow} \begin{gathered}
\\
\sigma_{k}:=\left\{E, C_{1}, \ldots, C_{k}\right\} \\
\sigma_{k} \text {-structure } \mathcal{G} \\
\psi_{k}\left(x_{1}, \ldots, x_{k}\right):=\bigwedge_{i=1}^{k} C_{i}\left(x_{i}\right) \wedge \bigwedge_{i \neq j} \neg E\left(x_{i}, x_{j}\right)
\end{gathered}
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Same approach as in [Durand, S., Segoufin, PODS'14], but now we have to take care of updates!

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## Representing Databases by Coloured Graphs

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\varphi\left(x_{1}, \ldots, x_{k}\right) \quad \equiv_{d} \bigvee_{i \in \mathcal{I}} \operatorname{sph}_{\tau_{i}}\left(x_{1}, \ldots, x_{k}\right) \quad \& \text { sentences }
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\operatorname{sph}_{\tau}\left(\bar{x}_{1}, \ldots, \bar{x}_{c}\right) & \equiv_{d} \bigwedge_{j \in\{1, \ldots, c\}} \operatorname{sph}_{\tau_{j}}\left(\bar{x}_{j}\right) \wedge \bigwedge_{j \neq j^{\prime}} \neg \operatorname{dist}_{\leqslant 2 r+1}\left(\bar{x}_{j}, \bar{x}_{j^{\prime}}\right)
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& V:=\bigcup_{j \in\{1, \ldots, c\}} \mathcal{C}_{j}^{\mathcal{G}_{D}} \quad E^{\mathcal{G}_{D}}:=\left\{\left(v_{\bar{a}}, v_{\bar{b}}\right) \in V^{2}: \operatorname{dist}^{D}(\bar{a}, \bar{b}) \leqslant 2 r+1\right\} \\
& \quad\left(\bar{a}_{1}, \ldots, \bar{a}_{c}\right) \in \operatorname{sph}_{\tau}(D) \quad \Longleftrightarrow \\
& \left(v_{\bar{a}_{1}}, \ldots, v_{\bar{a}_{c}}\right) \in \varphi_{c}\left(\mathcal{G}_{D}\right)
\end{aligned}
$$

## Updating the graph (1)

Claim
If $D_{\text {new }}$ is obtained from $D_{\text {old }}$ by one update step, then $\mathcal{G}_{D_{\text {new }}}$ can be obtained from $\mathcal{G}_{D_{\text {old }}}$ by $d^{\mathcal{O}\left(k^{2} r+k\|\sigma\|\right)}$ update steps and additional computing time $2^{\mathcal{O}\left(\|\sigma\| k^{2} d^{2 r+2}\right)}$.

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- Updating the colours:

$$
\text { 1: for } j=1 \text { to } c \text { do }
$$

2: $\quad$ for every tuple $\bar{b} \in \bigcup_{\ell=1}^{k} U^{\ell}$ do
3: $\quad$ if $\left(\mathcal{N}_{r}^{D_{\text {new }}}(\bar{b}), \bar{b}\right) \cong \tau_{j}$ then $C_{j} \leftarrow C_{j} \cup\left\{v_{\bar{b}}\right\}$
4: $\quad$ else $\quad C_{j} \leftarrow C_{j} \backslash\left\{v_{\bar{b}}\right\}$

Afterwards: $C_{j}=C_{j}^{\mathcal{G}_{\text {Dew }}}$

## Updating the graph (2)

- $E^{G_{D}}:=\left\{\left(v_{\bar{a}}, v_{b}\right) \in V^{2}: \operatorname{dist}^{D}(\bar{a}, \bar{b}) \leqslant 2 r+1\right\}$


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- Updating the edges: Before: $E=E^{\mathcal{G}_{D_{\text {old }}}}$
1: for every tuple $\bar{b} \in \bigcup_{\ell=1}^{k} U^{\ell}$ do
2: for every tuple $\bar{b}^{\prime} \in \bigcup_{\ell=1}^{k} U^{\ell}$ do
3: if condition (1), (2) and (3) holds then
4:
5:
6 :

$$
E \leftarrow E \cup\left\{\left(v_{\bar{b}}, v_{\bar{b}^{\prime}}\right)\right\}
$$

else

$$
E \leftarrow E \backslash\left\{\left(v_{\bar{b}}, v_{\bar{b}^{\prime}}\right)\right\}
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- Conditions:
(1) There is a $j \in\{1, \ldots, c\}$ such that $\bar{b} \in C_{j}^{\mathcal{G}}$
(2) There is a $j^{\prime} \in\{1, \ldots, c\}$ such that $\bar{b}^{\prime} \in C_{j^{\prime}}^{\mathcal{G}}$
(3) $\operatorname{dist}^{D_{\text {new }}}\left(\bar{b}, \bar{b}^{\prime}\right) \leqslant 2 r+1$


## Enumeration with delay $O\left(k^{3} d\right)$

$$
\psi_{k}\left(x_{1}, \ldots, x_{k}\right):=\bigwedge_{i=1}^{k} C_{i}\left(x_{i}\right) \wedge \bigwedge_{i \neq j} \neg E\left(x_{i}, x_{j}\right)
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for all $u_{1} \in C_{1}^{\mathcal{G}}$ do Enum $\left(u_{1}\right)$.
Output EOE.
function $\operatorname{Enum}\left(u_{1}, \ldots, u_{i}\right)$
if $i=k$ then
Output ( $u_{1}, \ldots, u_{i}$ )
else

$$
\begin{aligned}
& \text { for all } u_{i+1} \in C_{i+1}^{\mathcal{G}} \text { do } \\
& \quad \text { if } u_{i+1} \notin \bigcup_{j=1}^{i} N^{\mathcal{G}}\left(u_{j}\right) \text { then } \\
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\begin{gathered}
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i=1 \\
\text { Por all } u_{1}\left(x_{i}\right) \wedge C_{1}^{\mathcal{G}} \\
\text { Enum }\left(u_{1}\right) .
\end{gathered} \bigwedge_{i \neq j} \neg E\left(x_{i}, x_{j}\right)
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## Handling small colours

A colour $\ell \in\{1, \ldots, k\}$ is small $: \Longleftrightarrow\left|C_{\ell}^{\mathcal{G}}\right| \leqslant d k$

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$$
\mathcal{S}:=\left\{\left(u_{1}, \ldots, u_{s}\right) \in C_{1}^{\mathcal{G}} \times \cdots \times C_{s}^{\mathcal{G}}: \begin{array}{c}
\left(u_{j}, u_{j}\right) \notin E^{\mathcal{G}}, \\
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The set $\mathcal{S}$ can be computed in time $O\left((d k)^{k}\right)$.

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$$
\bar{s} \in \mathcal{S} \quad \Longleftrightarrow \quad \text { ex. } \bar{a} \text { such that }(\bar{s}, \bar{a}) \in \varphi(D)
$$

## The enumeration procedure

```
1: for all \(\left(u_{1}, \ldots, u_{s}\right) \in \mathcal{S}\) do
2: \(\quad \operatorname{Enum}\left(u_{1}, \ldots, u_{s}\right)\).
3: Output the end-of-enumeration message EOE.
4:
5: function \(\operatorname{Enum}\left(u_{1}, \ldots, u_{i}\right)\)
6: \(\quad\) if \(i=k\) then
7: output the tuple \(\left(u_{1}, \ldots, u_{i}\right)\)
8: else
9: \(\quad\) for all \(u_{i+1} \in C_{i+1}^{\mathcal{G}}\) do
10:
11:
if \(u_{i+1} \notin \bigcup_{j=1}^{i} N^{\mathcal{G}}\left(u_{j}\right)\) then
    Enum \(\left(u_{1}, \ldots, u_{i}, u_{i+1}\right)\)
where \(N^{\mathcal{G}}\left(u_{j}\right):=\left\{v \in V^{\mathcal{G}}:\left(u_{j}, v\right) \in E^{\mathcal{G}}\right\}\).
```

$$
\begin{aligned}
\psi_{k}\left(x_{1}, \ldots, x_{k}\right):= & \bigwedge_{i=1}^{\kappa} c_{i}\left(x_{i}\right) \wedge \bigwedge_{i \neq j} \neg E\left(x_{i}, x_{j}\right) \\
\mathcal{S} & \text { large colours }
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$$







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update step: Insert a node into a colour $C_{\ell}$ with $\left|C_{\ell}^{\mathcal{G}}\right|=d k$

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## Main result for enumeration

Theorem
There is a dynamic algorithm that receives as input

- a degree bound $d \geqslant 2$,
- a k-ary FO $+\mathrm{MOD}[\sigma]$-query $\varphi(\bar{x})$, and
- a db D of degree $\leqslant d$, and computes
- within $f(\varphi, d)\|D\|$ preprocessing time a data structure
- that can be updated in time $f(\varphi, d)$ and allows to enumerate $\varphi(D)$ with delay $O\left(k^{3}\right)$.

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f(\varphi, d)=3-\exp (\|\varphi\|+\lg \lg d)
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For enumeration with delay $O\left(k^{3}\right)$ : Use the skip-pointers that were introduced by [Durand, S., Segoufin, PODS'14] for the static setting and lift the approach to the dynamic setting.

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## Summary

 [Berkholz, Keppeler, S., ICDT'17]- Input:
- Database D
of degree $\leqslant d$
combined complexity
- query $\varphi\left(x_{1}, \ldots, x_{k}\right)$ in FO+MOD[ $\left.\sigma\right]$
- Preprocessing: $f(\varphi, d)=$ $3-\exp (\|\varphi\|+\lg \lg d)$ in time $f(\varphi, d)\|D\|$ Build a suitable data structure that represents $D$ and $\varphi(D)$
- Output:

For Boolean queries:

- Decide if $D \models \varphi$
in time $O(1)$
For $k$-ary queries:
- Compute the number of tuples in $\varphi(D)$
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- Test for a given tuple $\bar{a}$ whether $\bar{a} \in \varphi(D)$
in time $O\left(k^{2}\right)$
- Enumerate the tuples in $\varphi(D)$ with delay $O\left(k^{3}\right)$
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